

# Imperfect Repair Systems: Test and Model Selection

Enrico A. Colosimo  
(UFMG, Brazil)

Joint work: Gustavo Gilardoni (UnB), Maria Luiza Toledo (ENCE-IBGE) and Marta Freitas (UFMG), Brazil

Institut Polytechnique de Grenoble - Laboratoire Jean Kuntzmann  
Université Grenoble  
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# Research Team



- Prof. Gustavo Gilardoni (UnB)
- Profa. Maria Luiza Toledo (ENCE-IBGE)
- Postdoctoral researcher - Rodrigo Reis (UFMG)
- Profa. Marta Freitas (UFMG)

# Brazil



# Outline

- Motivating Situation: Dump Trucks Data
- Counting Process Formulation
- Non-parametric Test for Imperfect Repair
- ARA and ARI Classes of IR Models
- Models Selection/Reliability Prediction
- Dump Trucks Data Revisited
- Final Remarks

# Motivating situation

## Mining DUMP truck



# Motivating situation

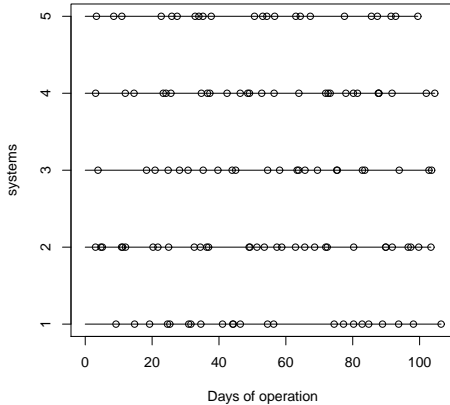
- ✓ Designed to operate in road conditions.
- ✓ DUMP trucks are used to transport mining production.
- ✓ In the mine under study, they are used in much more severe conditions.
- ✓ Engineering interest: engine failures.

## Motivating Situation (cont.)

### DATA SET

- ✓ Data collection in the period: July to October, 2012, for 5 trucks;
- ✓ the accumulated number of working days were registered;
- ✓ a total of 129 failures were observed, each one followed by a repair;

## Motivating situation (cont.)

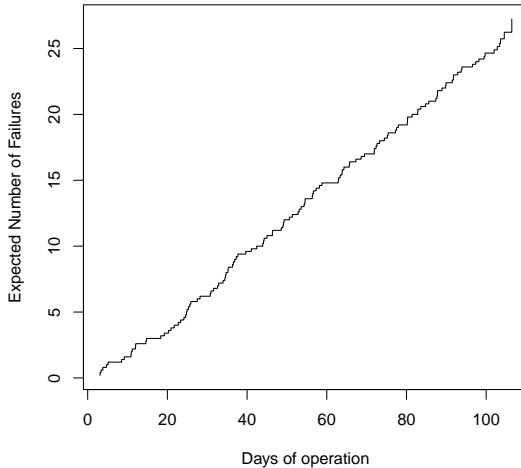


Failure times in days of operation (“o” are failures).



## Motivating situation (cont.)

### Empirical Mean Cumulative Function (MCF)



## Motivating situation (cont)

### OBJECTIVES

- ✓ Estimate the effect of the repairs and the aging speed of the engine's trucks.
- ✓ Estimate reliability predictors to provide information in order to base the decision-making process related to maintenance policies.

## Motivating situation (cont)

### Specific Objectives

- ✓ Is the repair imperfect or minimum?
- ✓ Reliability Prediction:
  - Model selection.
  - Estimate repair and age effects and reliability Predictors.

# General modeling of a counting process

- $N(t)$ : number of observed failures up to time  $t$ ;
- $\{N(t)\}_{t \geq 0}$ : counting processes that is characterized by the failure intensity function (Andersen et.al, 1993):

$$\lambda(t) = \lim_{h \rightarrow 0} \frac{P(N(t+h) - N(t) = 1 | \mathfrak{S}_t)}{h}, \quad \forall t \geq 0$$

where  $\mathfrak{S}_t$  is the history of the process up to time  $t$   
( $T_1 = t_1, \dots, T_{N(t)} = t_{N(t)}$ ).

## General modeling of a counting process (cont.)

- Cumulative Intensity:  $\Lambda(t) = \int_0^t \lambda(u) du$ .
- Mean Cumulative Intensity:  $\Phi(t) = E(N(t)) = E[\Lambda(t)]$ , (Aalen, 1978).
- ROCOF (rate of occurrence of failures) function is

$$\phi(t) = \Phi'(t) = E[\lambda(t)]$$

# Repair Types

## 1. Perfect Repair (PR)

- system leaves as it were new (As Good As New).
- Renew Process.

## 2. Minimal Repair (MR)

- system stays in the same condition as before the failure (As Bad As Old).
- NHPP:  $\phi(t) = \lambda(t)$ .

## 3. Imperfect Repair

- system leaves in a condition between ABAO and AGAN.
- Probably the one appropriate for the Mining Dump Truck, according to the maintenance engineers.

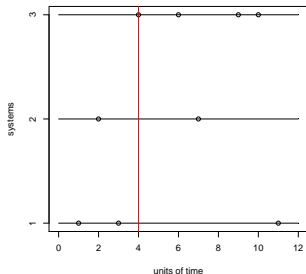
# Non-Parametric Test for Minimum Repair

$$H_0 : \text{MR} \quad \text{vs} \quad H_1 : \text{Non Harmful Repair/First Order}$$

It means:

- Non Harmful Repair: System reliability improves after repair.
- First Order:  $\lambda(t)$  just depend on the last failure,  $t_{N(t)}$ .

# Non-Parametric Test Idea



- Under  $H_0$ : MR, systems are a homogeneous NHPPs sample, with an increasing  $\lambda(t)$  in  $t$ .
- Under  $H_0$ : MR, each system would have the same probability to be the next failure's system.
- Under  $H_1$ : no harmful/first order repair, failure system will take longer time for the next failure as compared with the others.



# Notation and Assumptions

- ▶  $k$  identical repairable systems, where the failures history occurs independently;
- ▶ at each failure, a repair action of negligible length is performed;
- ▶  $n_i$  failures are observed in the  $i^{th}$  system,  $i = 1, 2, \dots, k$ ;
- ▶  $N = \sum_{i=1}^k n_i$  is the total number of observed failures in the systems.
- ▶ Let  $r_l$ ;  $l = 1, \dots, N$ , be the rank of the observed failure times in the overall sample;  $r_1 < r_2 < \dots < r_N$ .
- ▶  $Z_{i,l} = 1$  ( $G_l = i$ ), for the systems membership.

# Non-Parametric Test for Minimum Repair

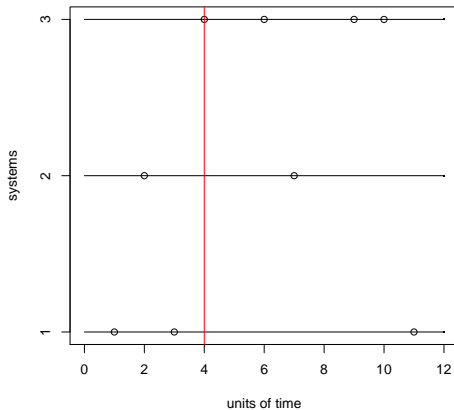
- Let's define,

$$X_l = \begin{cases} 1, & Z_{i,l} = Z_{i,l+1}, \text{ for all } i = 1, \dots, k \\ 0, & \text{otherwise} \end{cases} \quad (1)$$

for  $l = 1, \dots, N - 1$ .

- Let's define the test statistic:  $T = \sum_{l=1}^{N-1} X_l$ .

# Non-Parametric Test Idea



$X_1 = X_2 = X_3 = X_5 = X_6 = X_8 = 0$  and  $X_4 = X_7 = 1$  and  $T = 2$ .

# Non-Parametric Test

- Therefore, under  $H_0$ ,  $T$  has a  $\text{bin}(N - 1, \pi = 1/k)$ .
- Test can be reformulated in the following terms:

$$H_0 : \pi = \frac{1}{k} \text{ vs } H_1 : \pi < \frac{1}{k}.$$

- For an observed  $T=t$ , p-value =  $P(T \leq t | \pi = 1/k)$ .

# Non-Parametric Test for Minimum Repair

## Small size Monte Carlo Simulation

- Descriptive size evaluation of the test
- Scenarios
  - Number of systems:  $K=5,10$ ;
  - Truncation times:  $T=5,10,15$ ;
  - Power Law Process

$$\lambda(t) = \frac{\beta}{\eta} \left\{ \frac{t}{\eta} \right\}^{\beta-1}$$

- $\eta = 1$  and  $\beta = 1.5, 2$ ,
- 10000 replicates.

# Non-Parametric Test for Imperfect Repair

**Tabela:** Monte Carlo Simulation Results

Scenario			Covarage		$\hat{\Phi}/\text{System}$
			$\alpha = 0.05$	$\alpha = 0.10$	
$K = 5$	$T = 5$	$\beta = 1.5$	0.031	0.068	11
		$\beta = 2$	0.044	0.086	25
	$T = 10$	$\beta = 1.5$	0.039	0.085	31
		$\beta = 2$	0.046	0.090	100
	$T = 15$	$\beta = 1.5$	0.045	0.085	58
		$\beta = 2$	0.048	0.091	225
$K = 10$	$T = 5$	$\beta = 1.5$	0.035	0.074	11
		$\beta = 2$	0.039	0.083	25
	$T = 10$	$\beta = 1.5$	0.040	0.082	32
		$\beta = 2$	0.045	0.087	100
	$T = 15$	$\beta = 1.5$	0.044	0.090	58
		$\beta = 2$	0.046	0.095	225

- Dump trucks data: p-value = 0.08544. It is an indication against the hypothesis of minimum repair.

# Imperfect Repair (IR) Models

- ▶ Kijima *et al.* (1988) and Kijima (1989)
  - Virtual age models: rejuvenate the system after repair;
  - the degree of efficiency of the repair is represented by  $\theta$  ( $0 \leq \theta \leq 1$ ).
- ▶ Doyen and Gaudoin (2004): ARA and ARI classes of models.
  - start at  $t = 0$  with a initial intensity  $\lambda_R(t)$ .
  - has a rule to define how intensity changes immediately after a failure/repair.

## ARA class of models (Doyen and Gaudoin, 2004)

- ▶  $ARA_m$  model: repair reduces the increment in system age since the last  $m$  failures (memory parameter). Its failure intensity function is expressed by

$$\lambda_{ARA_m}(t) = \lambda_R(t - (1 - \theta) \sum_{j=0}^{Min(m-1, N(t)-1)} \theta^j T_{N(t)-j}).$$

- ▶ Virtual age model proposed by Kijima *et al.* (1988) corresponds to the  $ARA_1$  ( $m = 1$ ).



## ARI class of models (Doyen and Gaudoin, 2004)

- ▶ Repair action reduces the failure intensity function of the system;
- ▶ repair reduces the increment in failure intensity since the last  $m$  failures;
- ▶ Its failure intensity function is expressed by:

$$\lambda_{ARI_m}(t) = \lambda_R(t) - (1 - \theta) \sum_{j=0}^{Min(m-1, N(t)-1)} \theta^j \lambda_R(T_{N(t)-j}).$$

# Likelihood Function for a Counting Processes

- a counting process  $N(t)$  observed from 0 until a time  $T$ ,  
 $0 = t_0 < t_1 < \dots < t_{N(T)} \leq t^*$
- Lindqvist (2006), Andersen et al. (1993).
- ARA and ARI models.

# Likelihood function for the ARA class of models

$$\begin{aligned}
 L_{ARA_m}(\mu) &= \\
 &= \prod_{i=1}^k \prod_{j=1}^{n_i} \left\{ \lambda_R(t_{i,j} - (1-\theta) \sum_{p=0}^{\min(m-1, j-2)} \theta^p t_{i, j-1-p}) \times \right. \\
 &\quad \times e^{-\Lambda_R(t_{i,j} - (1-\theta) \sum_{p=0}^{\min(m-1, j-2)} \theta^p t_{i, j-1-p}) + \Lambda_R(t_{i, j-1} - (1-\theta) \sum_{p=0}^{\min(m-1, j-2)} \theta^p t_{i, j-1-p})} \} \times \\
 &\quad \times e^{-\Lambda_R(t_i^* - (1-\theta) \sum_{p=0}^{\min(m-1, n_i-1)} \theta^p t_{i, n_i-p}) + \Lambda_R(t_{i, n_i} - (1-\theta) \sum_{p=0}^{\min(m-1, n_i-1)} \theta^p t_{i, n_i-p})}
 \end{aligned}$$

# Likelihood function for the ARI class of models

$$\begin{aligned}
 L_{ARI_m}(\mu) &= \\
 &= \prod_{i=1}^k \prod_{j=1}^{n_i} \{ [\lambda_R(t_{i,j}) - (1-\theta) \sum_{p=0}^{\min(m-1, j-2)} \theta^p \lambda_R(t_{i, j-1-p})] \times \\
 &\times e^{-\Lambda_R(t_{i,j}) + \Lambda_R(t_{i, j-1}) + (1-\theta)[t_{i,j} - t_{i, j-1}] \sum_{p=0}^{\min(m-1, j-2)} \theta^p \lambda_R(t_{i, j-1-p})} \} \times \\
 &\times e^{-\Lambda_R(t_i^*) + \Lambda_R(t_{i, n_i}) + (1-\theta)[t_i^* - t_{i, n_i}] \sum_{p=0}^{\min(m-1, n_i-1)} \theta^p \lambda_R(t_{i, n_i-p})},
 \end{aligned}$$

# Parameter Estimation in ARA and ARI models

For both cases, the likelihood function was rewritten assuming a PLP parametric form for the initial intensity :

$$\lambda_R(t) = \frac{\beta}{\eta} \left\{ \frac{t}{\eta} \right\}^{\beta-1}$$

therefore,  $\mu = (\beta; \eta; \theta)$  is the vector of parameters to be estimated.

## Model selection

- maximum value of the estimated likelihoods:  $\hat{L} = L(\hat{\theta}; \hat{\beta}; \hat{\eta})$
- Burnham and Anderson (2004) : weight of evidence in favor of model  $r$ , given by:

$$w_r = \frac{\exp(-\Delta_r/2)}{\sum_{r=1}^R \exp(-\Delta_r/2)}$$

where

- $\Delta_r = \hat{L}_{max} - \hat{L}_r$ , ( $r = 1, \dots, R$ )
- and  $\hat{L}_{max}$  is the maximum of the  $R$  different  $\hat{L}$  values, considering that  $R$  different models were fitted.

This transformation forces the best model to have  $\Delta = 0$ , while the rest of the models have positive values.

## Model selection - Goodness-of-fit plot

- MCF  $\Phi(\cdot)$  is estimated to each model according to these steps:
  - ML estimates are obtained for a model from its observed failure data.
  - Observed failure data for the  $i$ -th system ( $i = 1, \dots, k$ ) and the MLEs are plugged in the model intensity function, providing  $\hat{\lambda}_i(t)$ .
  - $\hat{\Phi}_i(t)$  is computed as  $\int_0^t \hat{\lambda}_i(u) du$ , for  $0 \leq t \leq t_i^*$ .
  - Finally,  $\hat{\Phi}(t)$  is obtained as  $\frac{\sum_{i=1}^K \hat{\Phi}_i(t)}{K}$ .
- Plot of  $\hat{\Lambda}(t)$  against empirical MCF (Nelson-Aalen plot).

# Dump trucks data set revisited

The following models were considered:

- ▶  $ARA_m$ ;  $m = 1, \dots, 31$
- ▶  $ARl_m$ ;  $m = 1, \dots, 31$
- ▶ Minimal Repair ( $\theta = 1$ )

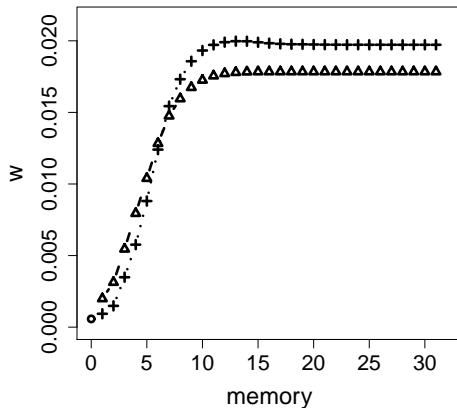
In cases 1) and 2),  $m = 31$  corresponds to  $m = \infty$  (max number of failures) and the PLP parametric form for the initial intensity was adopted.



**Tabela:** Results of the model fitting - Dump trucks data

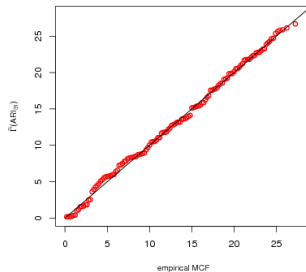
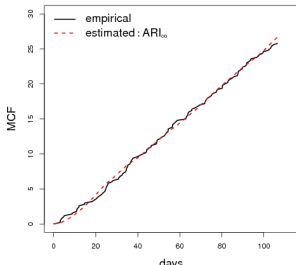
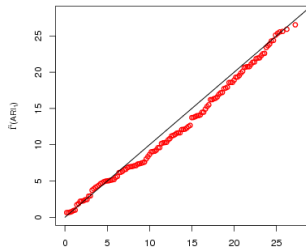
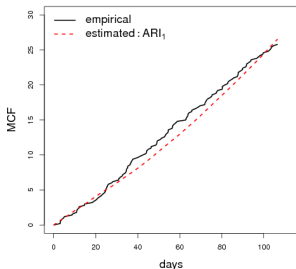
Estimated values	MODELS			
	MR	$ARA_1$	$ARA_{13}$	$ARA_{\infty}$
$\hat{\beta}$	1.14 [0.96;1.35]	1.33 [1.05;1.69]	1.80 [1.39;2.35]	1.81 [1.39;2.35]
$\hat{\eta}$	5.92 [3.54;9.93]	4.94 [3.41;7.15]	7.58 [5.35;10.76]	7.59 [5.35;10.79]
$\hat{\theta}$	- -	0.02 [0.0001;0.53]	0.60 [0.43;0.84]	0.60 [0.42;0.84]
$\hat{L}$	-307.1811	-304.7039	-300.3218	-300.3165
		$ARI_1$	$ARI_{13}$	$ARI_{\infty}$
$\hat{\beta}$		1.42 [1.06;1.91]	1.89 [1.69;2.11]	1.90 [1.71;2.11]
$\hat{\eta}$		4.18 [2.57; 6.79]	7.48 [5.74; 10.11]	7.65 [5.76;10.17]
$\hat{\theta}$		0.23 [0.05;1.00]	0.67 [0.52;0.87]	0.67 [0.52;0.87]
$\hat{L}$		-306.2146	-300.0904	-300.1155

## Dump trucks data set revisited (cont.)



**Figura:** Criterion value for model selection (0 - MR, + ARI and  $\Delta$  - ARA).

# Dump trucks data revisited (cont.) - GOF Plots



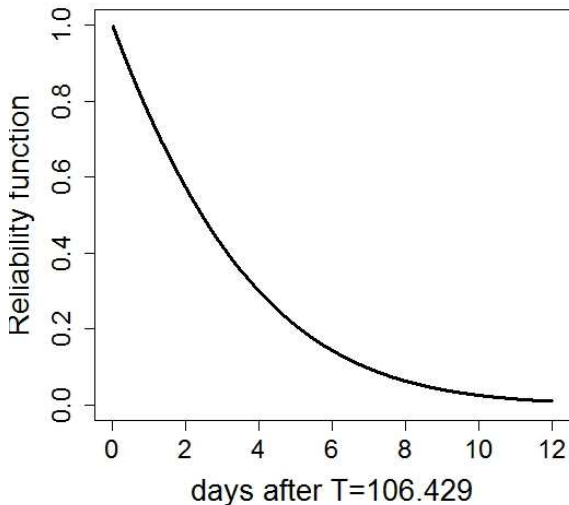
## Dump trucks data revisited (cont.)

- ▶ for  $ARI_{\infty}$ ,  $\hat{\beta} = 1.90$  ([1.71; 2.11]) , indicating that the equipment failure intensity function increases with time (intrinsic aging)
- ▶  $\hat{\theta} = 0.67$  ([0.52,0.87]). The repairs after failures tend to leave the equipment in a state between **AGAN** and **ABAO**

## Reliability Prediction Functions - ( $ARI_m$ class of models).

$$\begin{aligned} R_{T_n, ARI_m}(t) &= P(T_{n+1} - T_n > t | \mathfrak{S}_t) = P(N(T_n, T_n + t] = 0 | \mathfrak{S}_t) \\ &= \exp \left\{ \left( \frac{t_n}{\eta} \right)^\beta - \left( \frac{t_n + t}{\eta} \right)^\beta \right\} \times \\ &\times \exp \left\{ t(1 - \theta) \sum_{j=0}^{Min(m-1, n)-1} \theta^j \frac{\beta}{\eta} \left( \frac{t_{n-j}}{\eta} \right)^{\beta-1} \right\}. \end{aligned}$$

## Dump trucks data revisited (cont.)



## Final Remarks

- ✓ A Non-Parametric test for MR was proposed against the IR alternative.
- ✓ A extension of the test and a Graphical Technique are still under development.
- ✓ Imperfect Repair Classes of Models (ARA and ARI): Inference, models Selection and Reliability Predictors).
- ✓ Illustration in a real data set related to mining dump trucks.
- ✓ Effect of repair, aging speed and reliability predictor for maintenance policy were estimated for the dump trucks data.

## Author's Accepted Manuscript

ARA and ARI imperfect repair models: estimation, goodness-of-fit and reliability prediction

Maria Luíza Guerra de Toledo, Marta A. Freitas,  
Enrico A. Colosimo, Gustavo L. Gilardoni



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